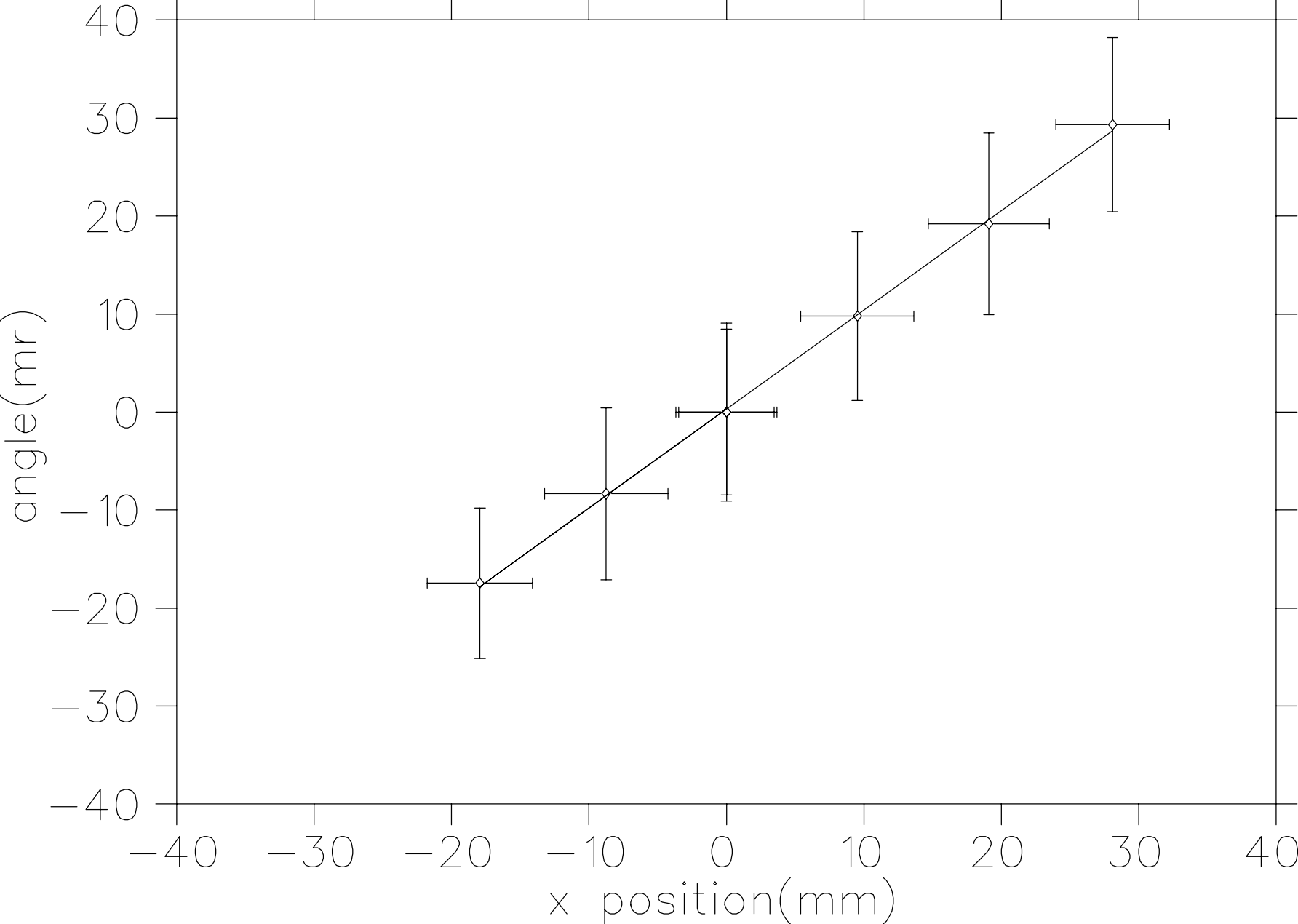
40
30
20
10
0
−10
−20
−30
−40
angle(mr)
−40
−30
−20
−10
0
10
20
30
40
x position(mm)