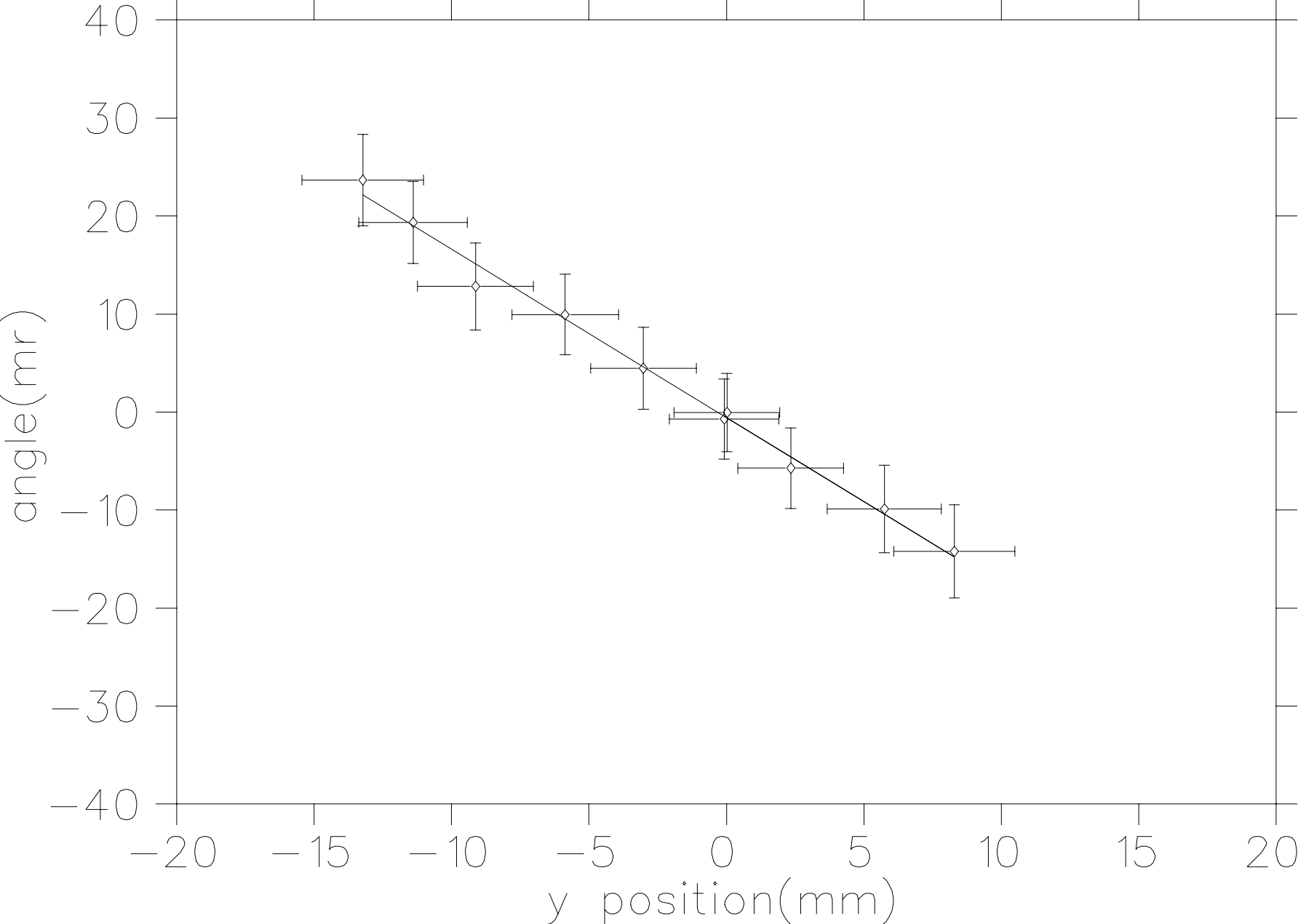
40
30
20
10
0
−10
−20
−30
−40
angle(mr)
−20
−15
−10
−5
0
5
10
15
20
y position(mm)