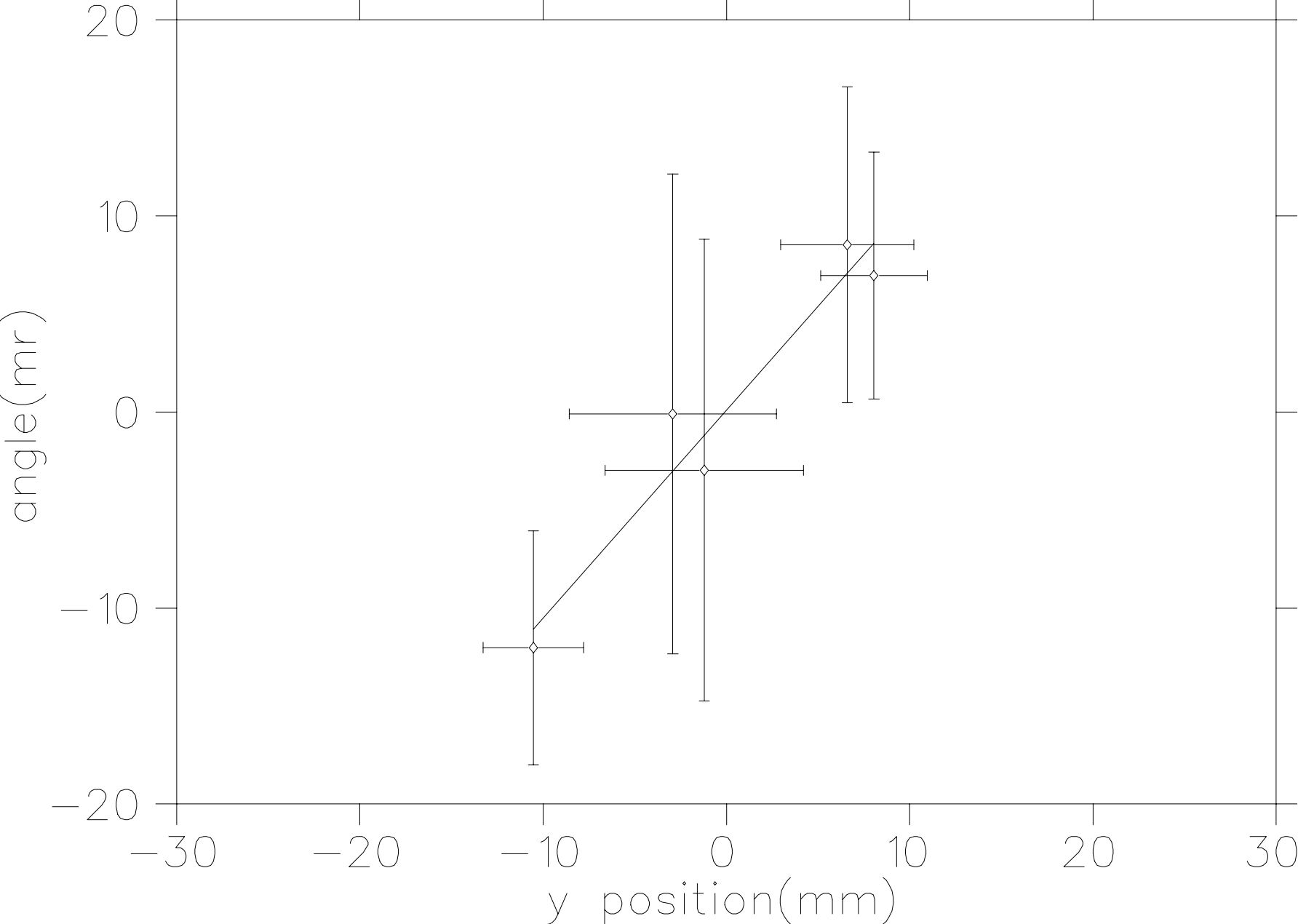
20
10
0
−10
−20
angle(mr)
−30
−20
−10
0
10
20
30
y position(mm)